

What is claimed is:

1 1 (currently amended). A device for processing a ~~the~~ surface of an object
2 comprising: ~~the~~
3 at least one processing station;
4 a conveying unit, by which ~~said~~ objects are transported into desired
5 positions at said processing stations;
6 a central controller, by which ~~the~~ functions of said conveying unit and of
7 said processing stations are synchronized by a clock pulse correlated with
8 transport of each said object and wherein said central controller controls each
9 said processing station.

2 (previously presented). The device according to claim 1, wherein said
processing station further comprises a printing unit.

3 (previously presented). The device according to claim 2, wherein at least
one of said printing units further comprises an inkjet printing head.

4 (previously presented). The device according to claim 3, wherein at least
one of said printing units further comprises a printing roller.

5 (previously presented). The device according to claim 3, wherein at least
one of said processing stations further comprises an inspection unit.

6 (previously presented). The device according to claim 1, wherein said
objects are symmetrical about a rotational axis.

7 (previously presented). The device according to claim 6, wherein said
objects are selected from the group consisting of beverage cans, beverage
bottles or cups.

8(previously presented). The device according to claim 1, wherein said conveying unit comprises a rotary cycle apparatus, on which said objects are arranged in the circumferential direction and may each be set into rotation by means of a conveyor drive means.

9(previously presented). The device according to claim 8, wherein said objects are each rotationally journalled with respect to their axis of rotation.

10(previously presented). The device according to claim 1, wherein starting signals are generated in the central controller, by which individual processing stations may be started independently.

1 11(currently amended). The device according to claim 1, wherein by
2 predetermining ~~a the~~ duration of ~~the~~ transmission of said clock pulse to a
3 processing station, ~~a the~~ duration of ~~a the~~ function of said processing station
4 may be predefined by the central controller.

1 12(currently amended). The device according to claim 11, wherein at least
2 one incremental encoder is provided for detecting ~~a the~~ rotary position of said
3 objects.

1 13(currently amended). The device according to claim 12, wherein said
2 conveyer drive means generate rotation in dependence upon ~~the~~ signals of
3 said incremental encoder for ~~are~~ position controlled.

1 14(previously presented). The device according to claim 13, wherein a lead
2 frequency defining the clock pulse may be preset by said central controller.

1 15(previously presented). The device according to claim 14, wherein said
2 lead frequency may be adjusted

1 16(currently amended). The device according to claim 14, wherein
2 ~~characterized in that~~ said lead frequency is transmitted to a computing unit for
3 synchronizing ~~the~~ rotation of said objects generated by said conveyer drive
4 means to said processing stations.

1 17(previously presented). The device according to claim 16, wherein said
2 computing unit is stationary.

1 18(previously presented). The device according to claim 16, wherein said
2 computing unit is arranged on said rotary cycle apparatus.

1 19(currently amended). The device according to claim 16, wherein said
2 lead frequency and the signals of said incremental encoders constitute input
3 quantities for ~~the~~ position control of the respective conveyer drive means.

1 20(currently amended). The device according to claim 16, wherein said
2 lead frequency may be adapted to ~~the~~ operating frequencies of said
3 processing stations.

1 21(previously presented). The device according to claim 20, wherein said
2 lead frequency is an operating frequency of inkjet droplets of an inkjet printing
3 head.

22-28: (Canceled)

29(previously presented). A device for processing the surface of an
object comprising;

at least one processing station;

a conveying unit, by which said object is transported into desired
positions at said processing station;

a central controller, by which the functions of said conveying unit and said processing stations are synchronized by presetting a clock pulse being correlated with the transport of said object, and wherein said central controller controls for each processing station; and,

wherein said clock pulse is derived from the cyclically and currently detected position values and detection times of the position values derived from the transport of the object being processed.

30(previously presented). The device according to claim 29, wherein the position values and the detection times of the position values of said objects are detected by an incremental encoder and stored as data sets in an evaluation unit.

31(previously presented). The device according to claim 30, wherein said clock pulse for a processing station comprises a series of counting pulses derived from the data sets stored in said evaluation unit and follow the increments of the respective incremental encoder.

32(previously presented). The device according to claim 31, wherein said counting pulses are generated in a frequency generator controlling a processing station.

33(previously presented). The device according to claim 32, wherein the output signals generated by said frequency generator are re-read into said central controller.

34(previously presented). The device according to claim 33, wherein control loops for generating said counting pulses are provided in said central controller, and wherein said re-read output signals of said frequency generators constitute instantaneous values of said control loops.

35(previously presented). The device according to claim 31, wherein the intervals of the individual counting pulses are shorter than the cycle time of said central controller.